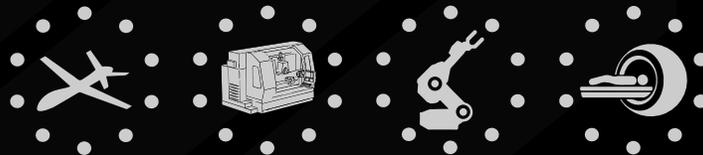


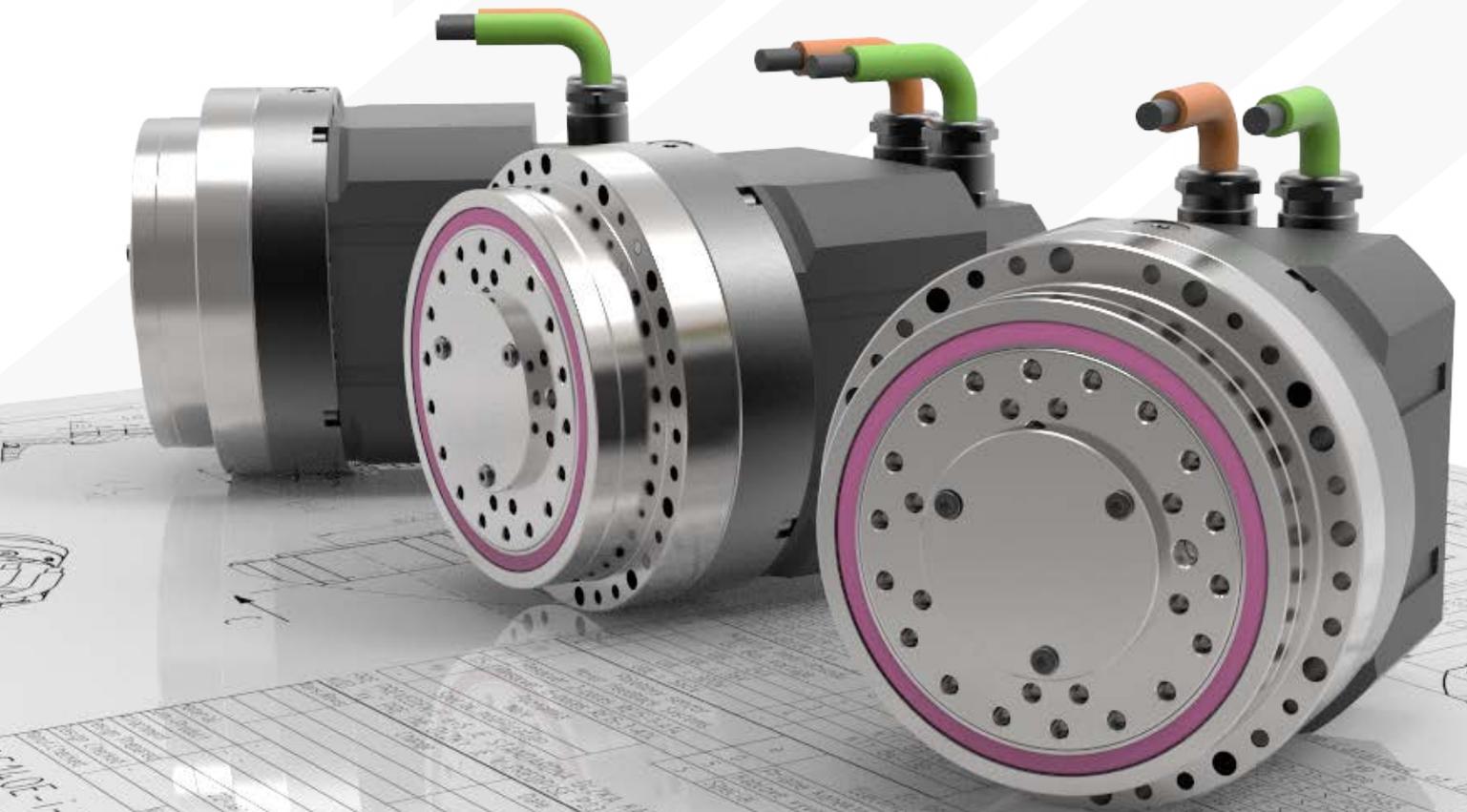


DriveSpin DS/DSH/DSM 140

The high precision **DriveSpin DS 140** actuators represent the new largest member of the DriveSpin product range, **meeting** even the most demanding **requirements** of customers from all industries. With their optimal **price/performance** ratio, they reliably provide parameters such as high accuracy and precision, high tilting and torsional stiffness, low weight, **compactness**, **low vibrations**, and a wide range of suitable technical solutions



- LOW LOST MOTION,
- LOW MOMENT OF INERTIA,
- HIGH REDUCTION RATIO,
- HIGH KINEMATIC ACCURACY,
- HIGH MOMENT OVERLOAD CAPACITY,
- HIGH CAPACITY OF THE INTEGRATED RADIAL-AXIAL OUTPUT BEARINGS,
- HIGH DYNAMIC PERFORMANCE.



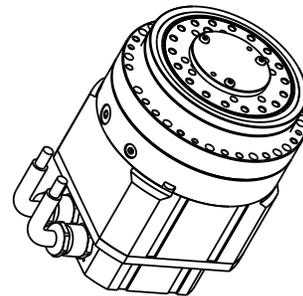
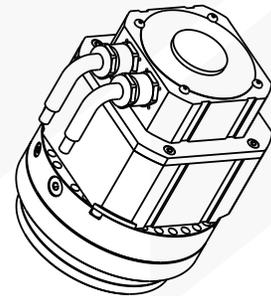
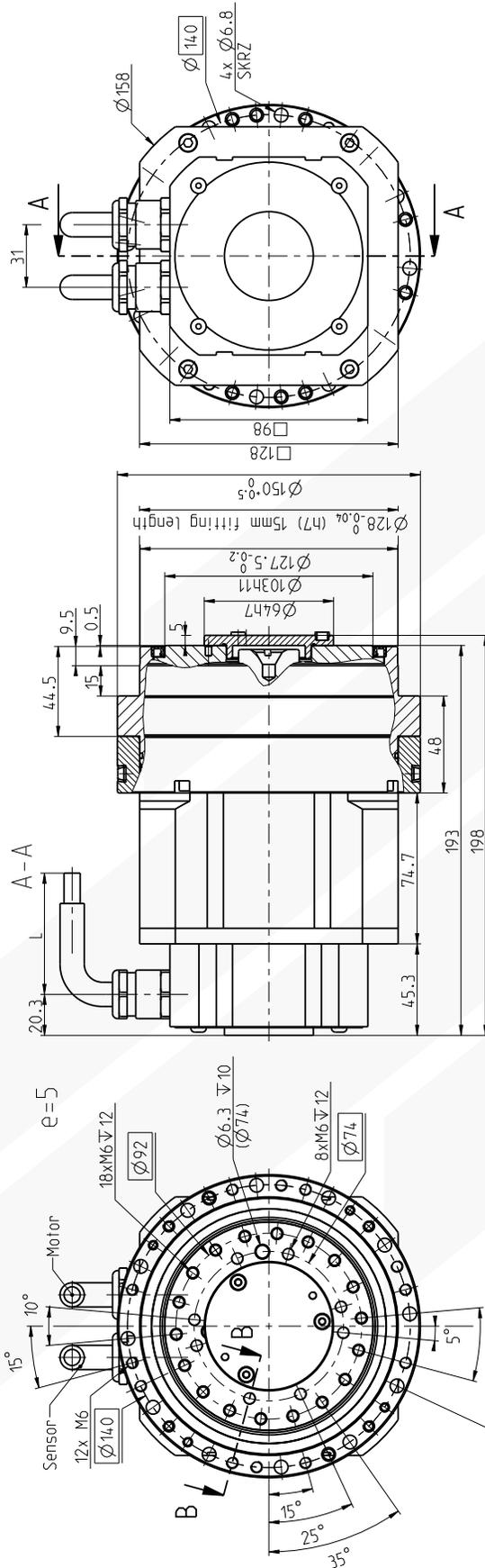
<p>SPINEA S.p.A. Via S. Felice 10, 20139 Milano, Italy Tel. +39 02 76001111 - Fax +39 02 76001112 Email: info@spinea.com - www.spinea.com</p>		<p>Model: DS-140-1000 Serial No.: 1000 Date: 10/10/2010</p>									
<p>Technical Data</p> <p>Power: 1000 W Voltage: 24 V DC Current: 41.7 A Speed: 1000 RPM Torque: 10 Nm Efficiency: 85% Protection: IP65</p>		<p>Dimensions</p> <p>Length: 140 mm Diameter: 100 mm Flange Thickness: 20 mm</p>									
<p>Material</p> <p>Body: Aluminum Flange: Steel</p>		<p>Accessories</p> <p>Wiring Harness: A-044-P00-#00-3 Mounting Bracket: B-001-001-001</p>									
<p>Notes</p> <p>1. See catalog for detailed specifications. 2. All dimensions are in millimeters unless otherwise specified. 3. Tolerances: ISO 2768-mS.</p>		<p>Revision History</p> <table border="1"> <tr> <th>Rev.</th> <th>Description</th> </tr> <tr> <td>01</td> <td>Initial design</td> </tr> <tr> <td>02</td> <td>Material change</td> </tr> <tr> <td>03</td> <td>Final design</td> </tr> </table>		Rev.	Description	01	Initial design	02	Material change	03	Final design
Rev.	Description										
01	Initial design										
02	Material change										
03	Final design										
<p>Customer Information</p> <p>Customer: A-044-P00-#00-3 Project: A-044-P00-#00-3 Drawing No: A-044-P00-#00-3</p>		<p>Approval</p> <p>Designed by: [Signature] Checked by: [Signature] Approved by: [Signature]</p>									



New
DS 140



DS 140



1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
D	S	*	-	1	4	0	-	0	6	7	-	3	1	B	0	7	6	-	1	2	-	X	X

Type designation
DS - standard

Reduction ratio
033
069
115

Brake
0: No
B: Yes

Special modification
Terminal cable length

Actuator size

Wiring diagram

DC bus voltage

- 1: 24 VDC
- 2: 36 VDC
- 3: 320 VDC
- 4: 560 VDC
- S: Special upon request

Type of electrical connection

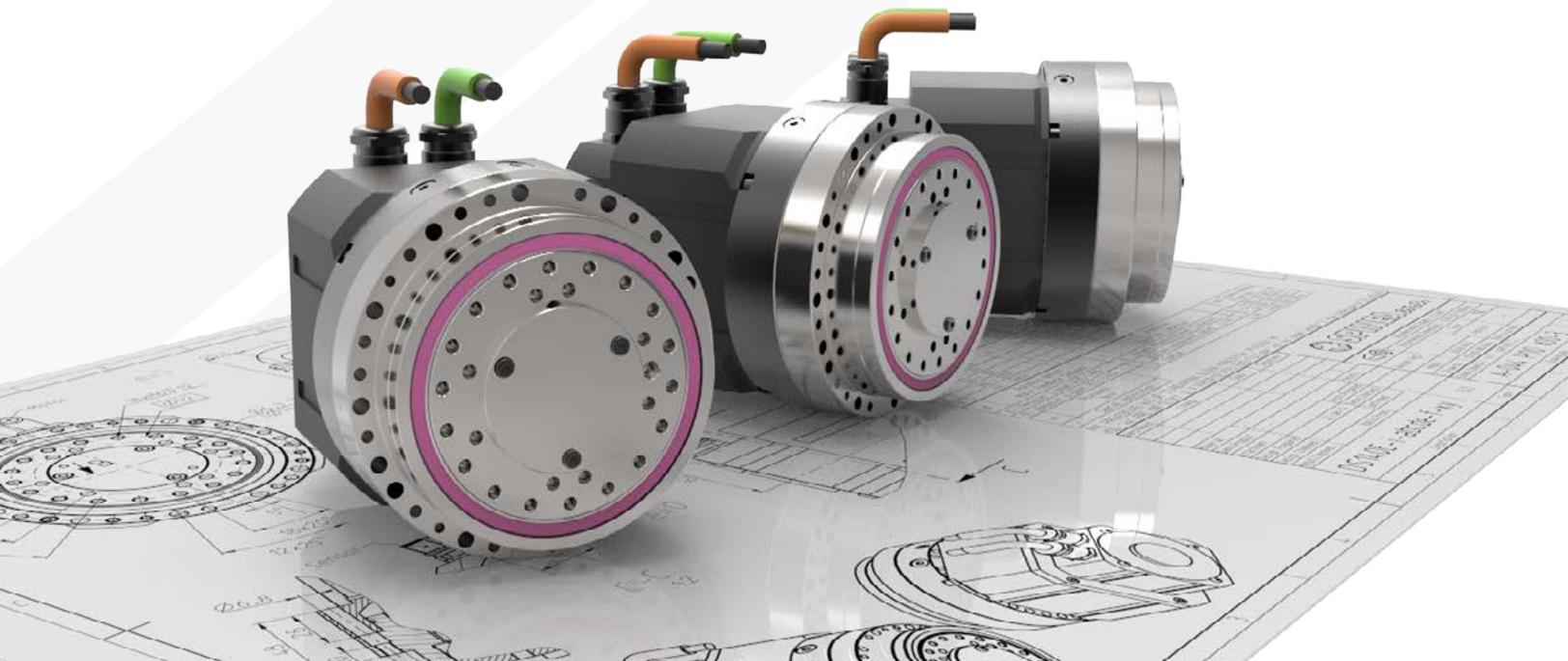
- 0: Straight connectors, perpendicular to the to centre line
- 4: Angled rotatable connectors
- 5: With terminal cable (L = 1 m)
- S: Special upon request

Temperature sensor

- 1: PTC 11-K13
- 3: KTY 83-110
- 4: KTY 84-130

Sensor type

Resolver, Endat®, HIPERFACE®



DS 140 MAIN PARAMETERS

DS Actuator			DS 140/DSH 140/DSM 140			
Reduction ratio	I		69, 115			
Rated output torque	T_r	Nm	268			
Acceleration/braking output torque	T_{max}	Nm	670			
Rated input speed of the reduction gear	n_r	min^{-1}	2000			
Maximum allowed input speed of the reduction gear	n_{max}	min^{-1}	3000/4500			
Tilting stiffness 1) 5)	M_t	Nm/arcmin	380			
Torsional stiffness 1) 6)	k_t	Nm/arcmin	62			
Maximum lost motion	LM	arcmin	<1.0			
Hysteresis	H	arcmin	<1.0			
Maximum tilting moment 2) 3)	$M_{c,max}$	Nm	1160			
Rated radial force 2)	F_{rR}	kN	11.5			
Maximum axial force 2) 4)	$F_{a,max}$	kN	17			
Allowed temperature range		$^{\circ}\text{C}$	-10 $^{\circ}\text{C}$ to +40 $^{\circ}\text{C}$			
Reduction gear maximum allowed temperature		$^{\circ}\text{C}$	65 $^{\circ}\text{C}$			
Servo inverter DC bus voltage	U_{dc}	V	24	36	320	560
Protection class			IP64 as standard			
Lubricant			Grease Castrol Optitemp TT1, PDO			
Paint			black RAL 9005			
Insulation class			F			

SUBJECT TO CHANGES WITHOUT PRIOR NOTICE

- 1) Mean statistical value. For further information, see Chapter 9, Tilting Stiffness and Torsional Stiffness.
- 2) Load at output speed 15 rpm.
- 3) Tilting moment $M_{c,max}$ value at $F_a=0$. If $F_a \neq 0$ see Chapter 9, Tilting Moment, of this document.
- 4) Axial force $F_{a,max}$ value at $M_c=0$. If $M_c \neq 0$ see Chapter 9, Tilting Moment, of this document.
- 5) The parameter depends on the high precision reduction gear model.
- 6) The parameter depends on the high precision reduction gear model, reduction ratio, and lost motion value.

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